

# FEEDBACK FROM REAL-TIME EXPERIMENTS

Camille MONIÈRE, PhD Student

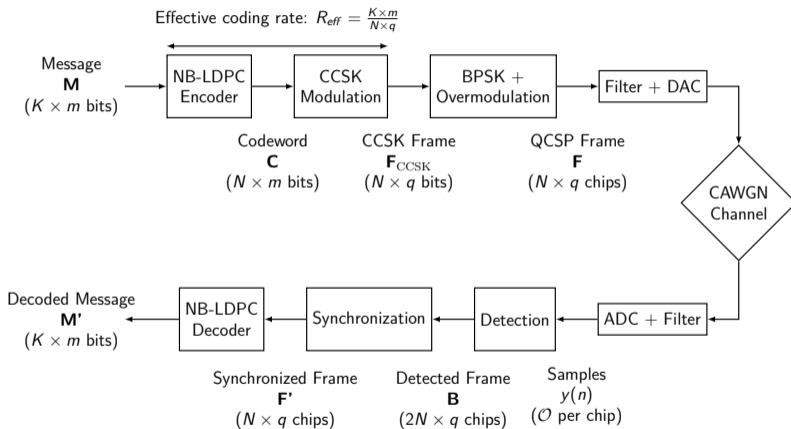
Lab-STICC, CNRS UMR 6285      IMS, CNRS UMR 5218  
Université de Bretagne Sud, France      Université de Bordeaux, France  
10/06/2022

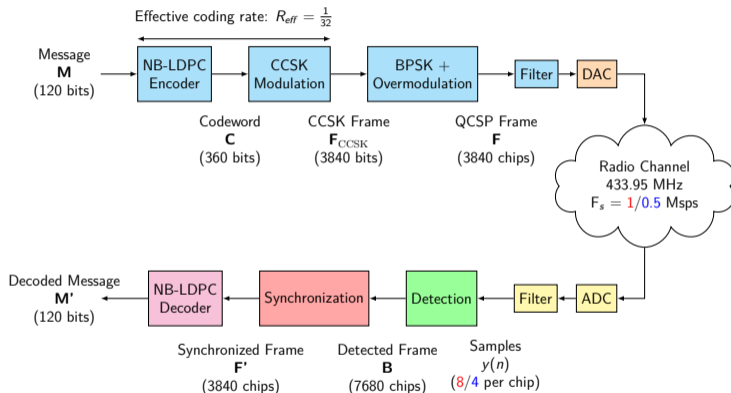
QCSP Meeting,  
LETI, Grenoble, France



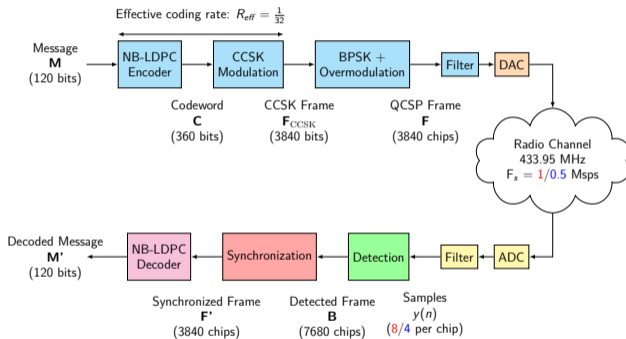
# SOMMAIRE

- 1 CONTEXT
  - QCSP System Model
  - Implementation
- 2 EXPERIMENTS
  - Detection Critical Point: Threshold
  - Urban Area Experiments
- 3 CONCLUSION





- $K = 20$
- $m = 6$
- $N = 60$
- $q = 2^m = 64$
- $R_{eff} = \frac{1}{32}$
- $\mathcal{O} = 8$  or  $4$



## LEGEND

Transmitter

Receiver

C/C++

VHDL and  
C++ HLS

VHDL

C/C++

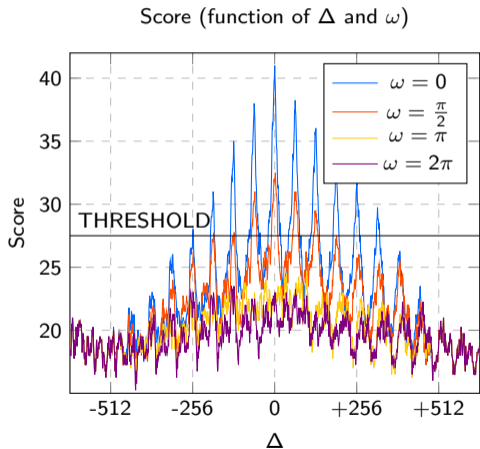
MATLAB

C/C++ called  
from MATLAB

$F_s = 1$  Msp but only half of the samples are used in detection resulting in  $F'_s = .5$  Msp

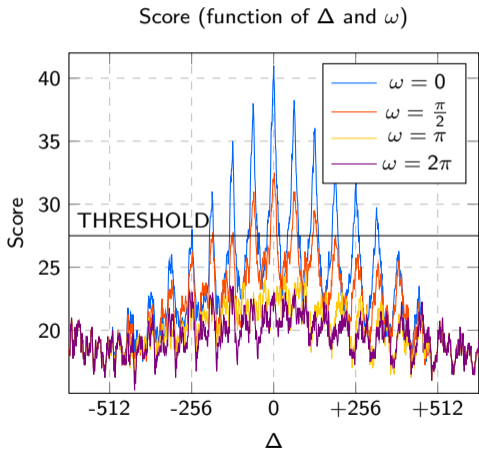
Detection Critical Point: Threshold

# Issue



Threshold can be calculated from synthetic values but ...

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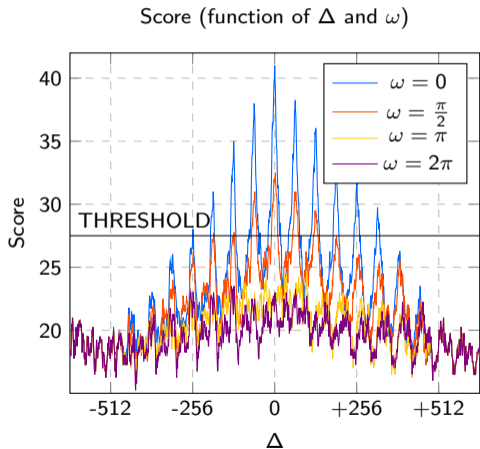
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- Radio channel in urban area is not Gaussian,





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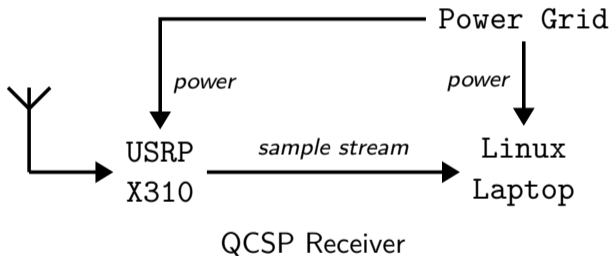
Threshold can be calculated from synthetic values but ...

- Radio channel in urban area is not Gaussian,
- oversampling was not considered.

A criterion to set the threshold is needed:



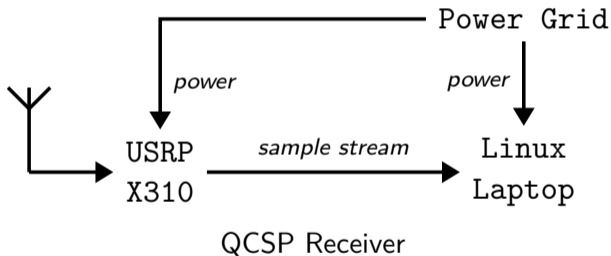
# Protocol: Measuring the MTBFA



- No QCSP transmission,
- uncontrolled environment (office),
- free running detector.

Detections (*thus, false alarms*) are counted. After 100 false alarms or 5 hours elapsed, a new threshold is tested.

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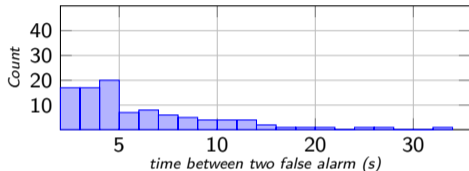
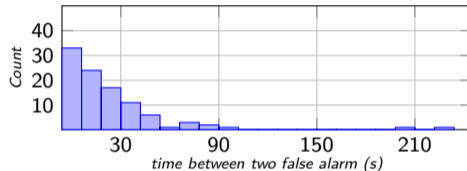
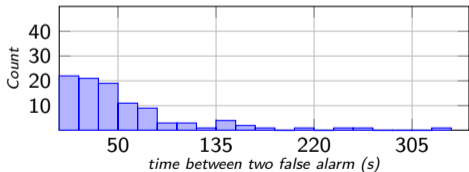
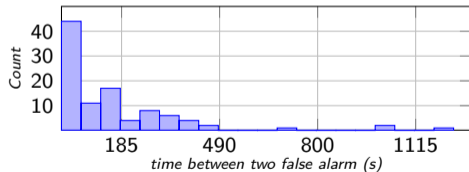


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Detection Critical Point: Threshold

# Results for four different thresholds, receiver gain maxed-out

Threshold = 140.00  $\Rightarrow$  MTBFA = 7.35 sThreshold = 141.00  $\Rightarrow$  MTBFA = 26.92 sThreshold = 141.25  $\Rightarrow$  MTBFA = 55.82 sThreshold = 142.00  $\Rightarrow$  MTBFA = 160.78 s

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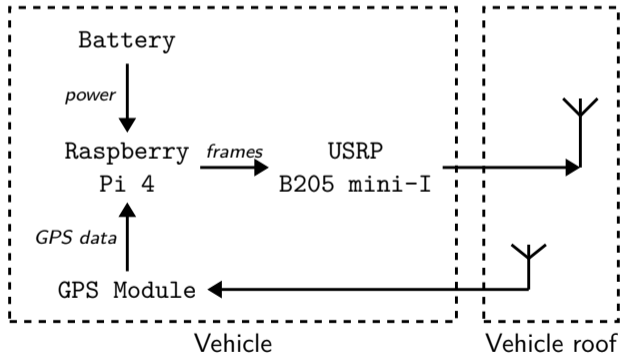
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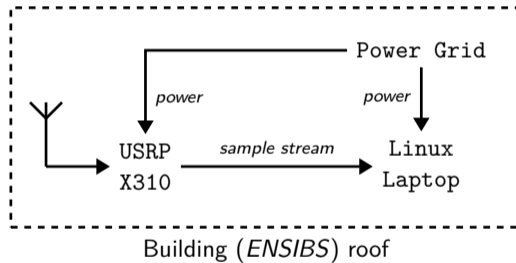
Best way to know is to test it in real conditions!

# Transmitter

Standalone, embedded in a car moving through the town.

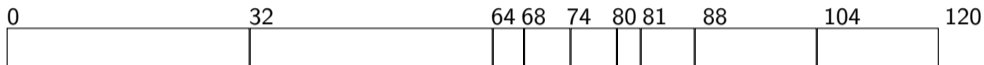


# Receiver

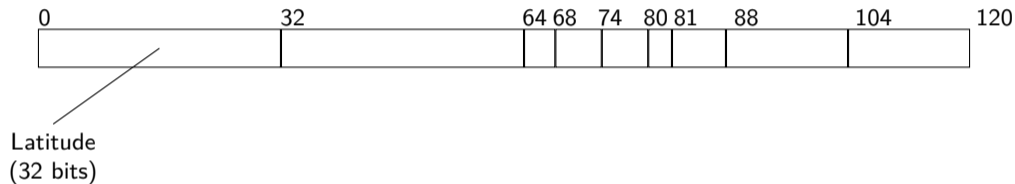




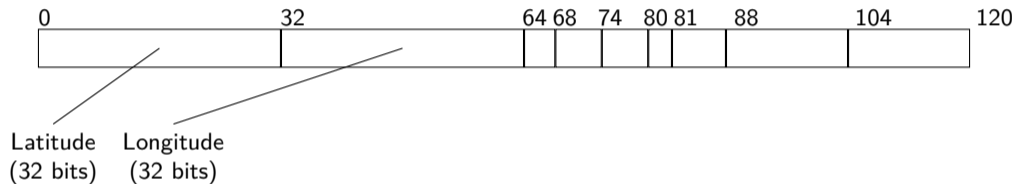
# Sent Data



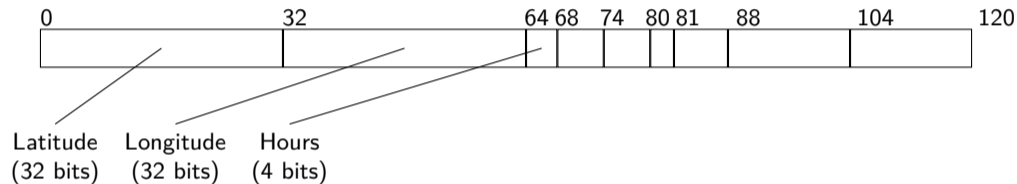
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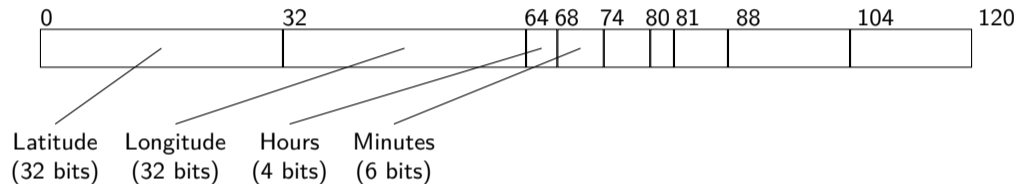


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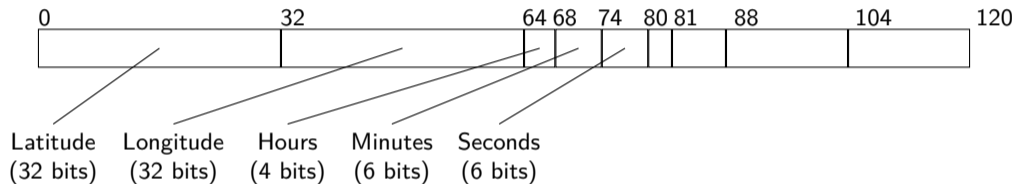




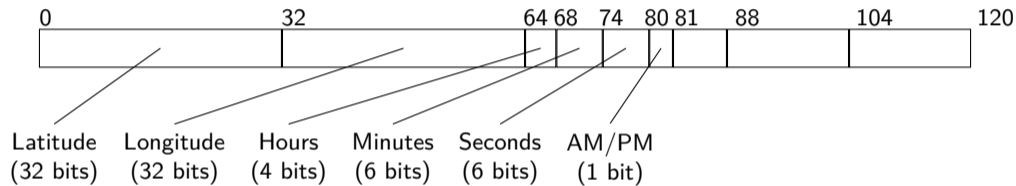
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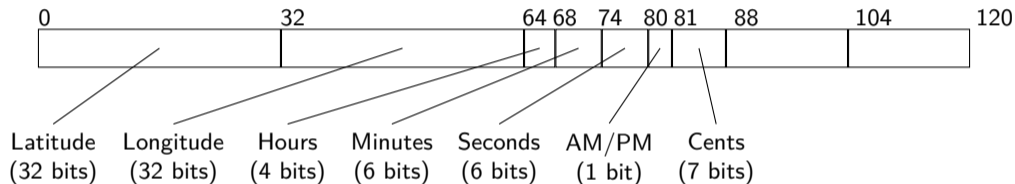
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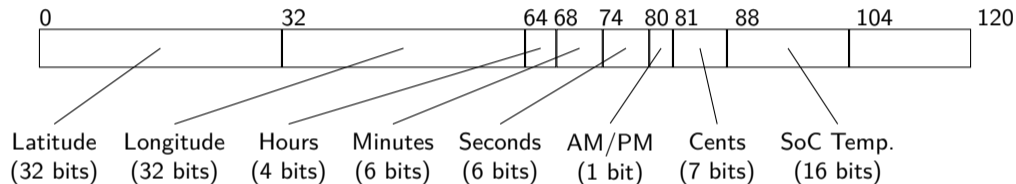
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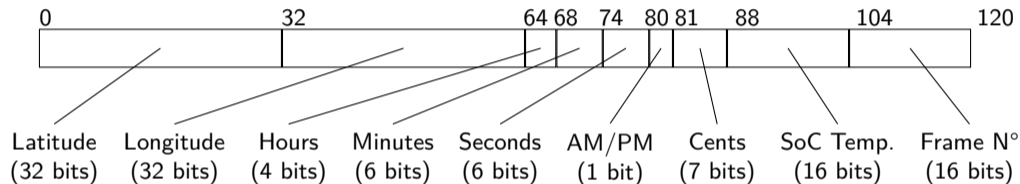
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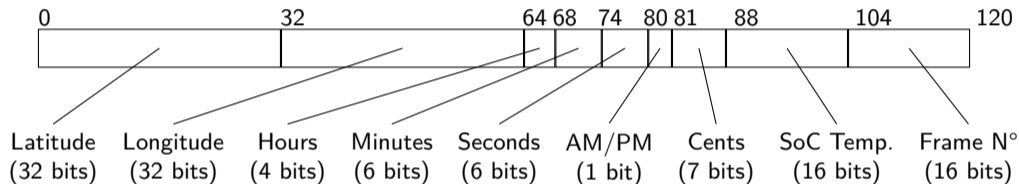
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# Sent Data



# Sent Data



GPS module is used to fetch latitude and longitude, while other information are given by the RPi4 SoC.

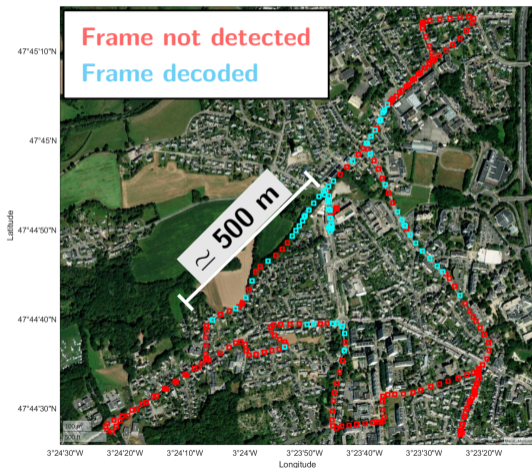
Note: The track is also recorded by an independent smartphone in the car, as redundancy.





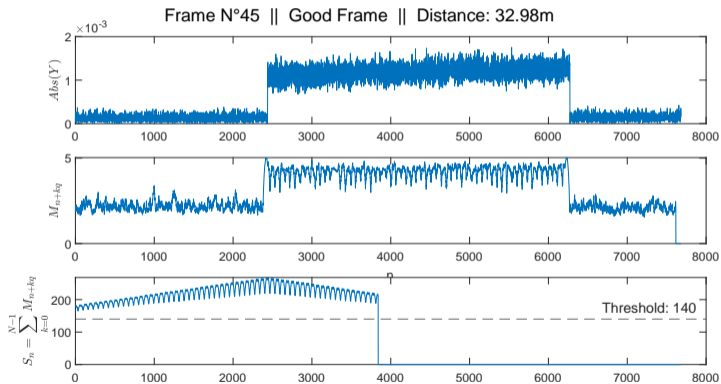


# Second Experiment

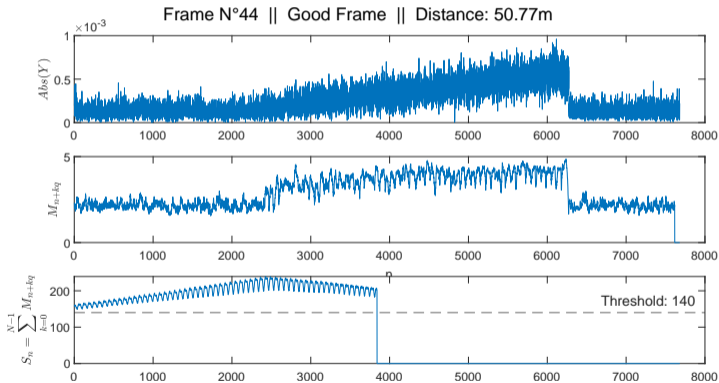


- Locations directly extracted from frames and frames logged by the transmitter,
- detection data are also logged,
- a maximum range of up to 500 m, expected due too antennas poorer quality.

# Second Experiment: Frame examples

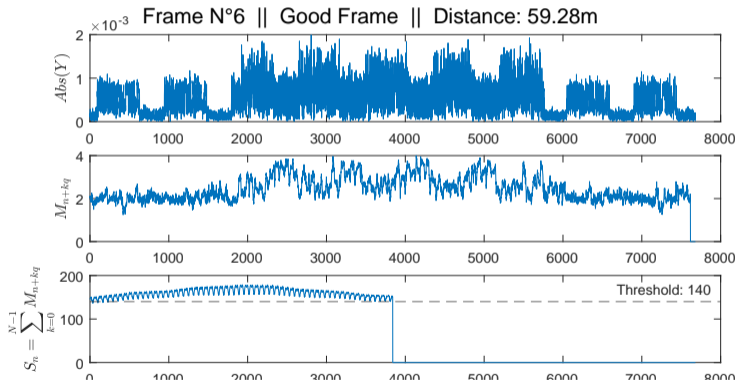


# Second Experiment: Frame examples





# Second Experiment: Frame examples



# Overall ranges



Range difference are related to the antennas.

Thus, a lower bound for the range of 500 m can be defined.

For a consumption lower than  $1 \mu\text{J}$  per information bit, it is promising.

*Transmitter power have been measured to 4 dBm when transmitting a QCSP frame for the chosen settings, and for the given data rate, a frame takes 30 ms to be emitted.*

# Conclusion

It Just Works™



# Conclusion

- A full **real time** prototype is ready,
- not the sexiest (hybrid, not fully embedded, MATLAB)
- but already good enough to draw attention.
- Bonus: logged data already allow further explorations.

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Yay!



## Futur Points of Interest

- A retro-engineered LoRa-like communication stack will be tested following the same protocol, to make comparisons.
- The hardware detector is nearly there (and can theoretically achieve throughput up to 200MChip/s, with the resources).
- TO CHECK: QCSP reception seems to be more resilient to saturation than (for example) LoRa-like transmissions.

# References

- [1] Michael Fingeroff. *High-Level Synthesis Blue Book*. New Jersey: Xlibris Corporation, 2010. ISBN: 978-1-4500-9724-6 978-1-4500-9723-9.
- [2] “IEEE Std 802.15.4-2020, IEEE Standard for Low-Rate Wireless Networks”. In: (May 2020), p. 799.
- [3] Camille Monière et al. “Time Sliding Window for the Detection of CCSK Frames”. In: *IEEE Workshop on Signal Processing Systems (SiPS'2021)*. Combra, Portugal, Oct. 2021.
- [4] *OpenStreetMap*. <https://www.openstreetmap.org/copyright>.
- [5] Kassem Saied. “Quasi-Cyclic Short Packet (QCSP) Transmission for IoT”. Theses. Université Bretagne Sud, Mar. 2022.
- [6] Xilinx. *Vivado Design Suite User Guide: High-Level Synthesis (UG902)*. 2019.

Thank you, have you any question?