

FEEDBACK FROM REAL-TIME EXPERIMENTS

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Sommaire



- $\bullet~\mathrm{QCSP}$ System Model
- Implementation

2 Experiments

- Detection Critical Point: Threshold
- Urban Area Experiments

3 CONCLUSION

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 $F_s = 1$ Msps but only half of the samples are used in detection resulting in $F'_s = .5$ Msps

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Detection Critical Point: Threshold			

Issue

Score (function of Δ and ω)



Threshold can be calculated from synthetic values but . . .

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Score (function of Δ and ω)



Threshold can be calculated from synthetic values but ...

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• Radio channel in urban area is not Gaussian,

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Issue

Score (function of Δ and ω)



Threshold can be calculated from synthetic values but ...

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- Radio channel in urban area is not Gaussian,
- oversampling was not considered.

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A criterion to set the threshold is needed:

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Issue

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A criterion to set the threshold is needed:

MTBFA: Mean Time Between False Alarms

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Protocol: Measuring the MTBFA



- No QCSP transmission,
- uncontrolled environment (office),
- free running detector.

Detections (*thus, false alarms*) are counted. After 100 false alarms or 5 hours elapsed, a new threshold is tested.

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Protocol: Measuring the MTBFA



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CONTEXT O Detection Critical Point: Threshold Experiments

Conclusion

Results for four different thresholds, receiver gain maxed-out

Threshold = $140.00 \Rightarrow MTBFA = 7.35 s$ Count Count time between two false alarm (s) Threshold = $141.25 \Rightarrow MTBFA = 55.82 s$ Count Count time between two false alarm (s)

Threshold = $141.00 \Rightarrow MTBFA = 26.92 s$



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Feedback from real-time experiments



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• Does it work?

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- Does it work?
- Is it resilient to the channel evolution?



• Does it work?

Best way to know is to test it in real conditions!

• Is it resilient to the channel evolution?

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Transmitter

Standalone, embedded in a car moving through the town.



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0	32	64	68	74	80	81	88	104	120

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GPS module is used to fetch latitude and longitude, while other information are given by the RPi4 SoC.

Note: The track is also recorded by an independent smartphone in the car, as redundancy.

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Two experiments made:



- Blue track:
 - 15/04/2022,
 - receiver's antenna is disposed on a ground plane,
 - GPS module failed ...
- Ø Magenta track:
 - 30/05/2022,
 - receiver's antenna is plugged directly on the radio device,

- transmitter antenna was damaged,
- everything else was fine.

Conclusion 000

First Experiment



- Locations retrieved from the time extracted from the frames crossed with the time-stamps of the smartphone GPS data,
- locations are coherent with the live tracking done by phone during the experiment,
- a maximum range of up to 1 km has been achieved.

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Second Experiment



- Locations directly extracted from frames and frames logged by the transmitter,
- detection data are also logged,
- a maximum range of up to 500 m, expected due too antennas poorer quality.

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Second Experiment: Frame examples



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Second Experiment: Frame examples



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Second Experiment: Frame examples



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1 km .5 km

Range difference are related to the antennas.

Thus, a lower bound for the range of 500 m can be defined.

For a consumption lower than 1 μ J per information bit, it is promising.

Transmitter power have been measured to 4 dBm when

transmitting a QCSP frame for the chosen settings, and for the given data rate. a frame takes 30 ms to be emitted.

Overall ranges

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It Just WorksTM

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- A full real time prototype is ready,
- not the sexiest (hybrid, not fully embedded, MATLAB)
- but already good enough to draw attention.
- Bonus: logged data already allow further explorations.

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Conclusion

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Futur Points of Interest

 \rightarrow A retro-engineered LoRa-like communication stack will be tested following the same protocol, to make comparisons.

 \rightarrow The hardware detector is nearly there (and can theoretically achieve throughput up to 200MChip/s, with the resources).

 \rightarrow TO CHECK: QCSP reception seems to be more resilient to saturation than (for example) LoRa-like transmissions.

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Thank you, have you any question?

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